

Data Simulation

This section describes the steps to simulate occurrence data for fitting spatially explicit occupancy models in [R-INLA](#).

Set up

```
# Load the libraries
library(INLA)
library(inlabru)
library(fmesh)
library(spatstat)
library(sf)
library(terra)
library(ggplot2)
library(tidyverse)
library(gt)
library(dplyr)
library(viridis)
library(viridisLite)
library(scico)
library(patchwork)
```

Define the spatial domain and the regular lattice by setting a 300×300 study area divided into 5×5 grid cells.

```
# Define spatial domain
win <- owin(c(0,300), c(0,300))
npix <- 1000

Domain <- rast(nrows=npix, ncols=npix,
                 xmax=win$xrange[2], xmin=win$xrange[1],
```

```

ymax = win$yrange[2], ymin=win$yrange[1])

values(Domain) <- 1:ncell(Domain)
xy <- crds(Domain)

# Define regular grid
cell_size = 3
customGrid <- st_make_grid(Domain, cellsize = c(cell_size, cell_size)) %>%
  st_cast("MULTIPOLYGON") %>%
  st_sf() %>%
  mutate(cellid = row_number())

# number of cells
nCells <- nrow(customGrid)

```

Simulated study area

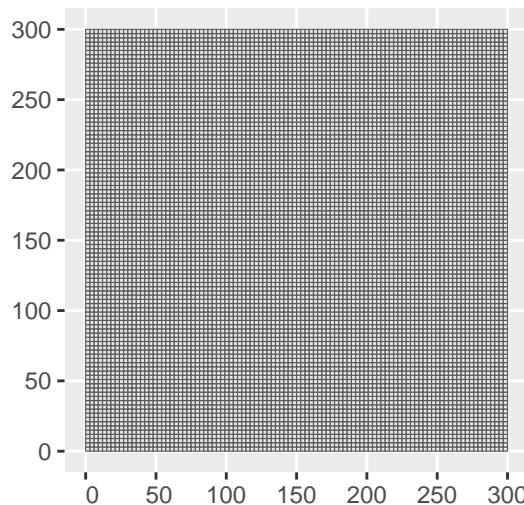


Figure 1: Custom 5^2 units regular grid over a 300^2 area .

Simulate data for a simple spatial occupancy model

We simulate three different Gaussian Markov Random fields (GMRF) using the `inla.qsample` function.

```

# Spatial boundary
boundary_sf = st_bbox(c(xmin = 0, xmax = 300, ymax = 0, ymin = 300)) |>
  st_as_sfc()

# Create a fine mesh
mesh_sim = fm_mesh_2d(loc.domain = st_coordinates(boundary_sf)[,1:2],
                      offset = c(-0.1, -.2),
                      max.edge = c(4, 50))

# Matern model
matern_sim <- inla.spde2.pcmatern(mesh_sim,
                                      prior.range = c(100, 0.5),
                                      prior.sigma = c(1, 0.5))

range_spde = 100
sigma_spde = 1

# Precision matrix
Q = inla.spde.precision(matern_sim, theta = c(log(range_spde),
                                                log(sigma_spde)))

# Simulate three spatial fields
seed = 12345
sim_field = inla.qsample(n = 3, Q = Q, seed = seed)

```

Create the projector matrix A_{proj} using the centroid of each grid cell as coordinates and compute the spatial random effect $\omega(s)$, spatial environmental covariate $x(s)$ and spatial detection covariate $g(s)$ (Figure 2). (Note: Covariates $x(s)$ and $g(s)$ are stored as raster data).

```

# Obtain the centroid of each cell
coord_grid = st_coordinates(customGrid |> st_centroid())
# A matrix
A_proj = inla.spde.make.A(mesh_sim, loc = coord_grid)

# Spatial components
omega_s = (A_proj %*% sim_field)[,1] # spatial random field
x_s = (A_proj %*% sim_field)[,2] # spatial environmental covariate
g_s = (A_proj %*% sim_field)[,3] # spatial detection covariate

# create rasters
x_rast = rast(data.frame(x = coord_grid[,1], y = coord_grid[,2], x_s))
g_rast = rast(data.frame(x = coord_grid[,1], y = coord_grid[,2], g_s))

```

```

# save raster data

writeRaster(x_rast,filename = paste('raster data','x_covariat.tif',sep='/'),
            overwrite=TRUE)
writeRaster(g_rast,filename = paste('raster data','g_covariat.tif',sep='/'),overwrite=TRUE)

```

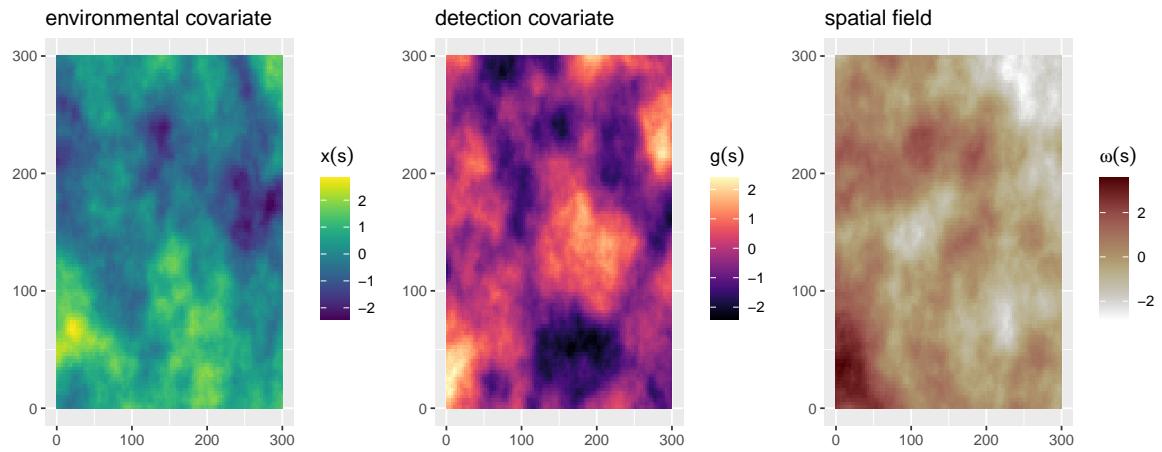


Figure 2: Simulated spatial environmental and detection covariates and spatial random field.

Occurrence data is simulated from the following occupancy model:

$$\text{State process: } \begin{cases} z_i \sim \text{Bernoulli}(\psi_i) \\ \text{logit}(\psi_i) = \beta_0 + \beta_1 x(s) + \omega(s) \end{cases}$$

$$\text{Observational process: } \begin{cases} y_i \sim \text{Binomial}(K_i, z_i \times p_i) \\ \text{logit}(p_i) = \alpha_0 + \alpha_1 g(s) \end{cases}$$

State process model sub-component

Define model parameters β and compute the occupancy probabilities ψ and occupancy states z (Figure 3)

```

# State process model coefficients
beta <- c(NA,NA)
beta[1] <- qlogis(0.3) # Base line occupancy probability
beta[2] <- 1.5 # environmental covariate effect

```

```

# Occupancy probabilities
psi <- inla.link.logit(beta[1] + beta[2]*x_s + omega_s, inverse = T)

# True occupancy state

set.seed(seed)
z <- rbinom(ncells, size = 1, prob = psi)

```

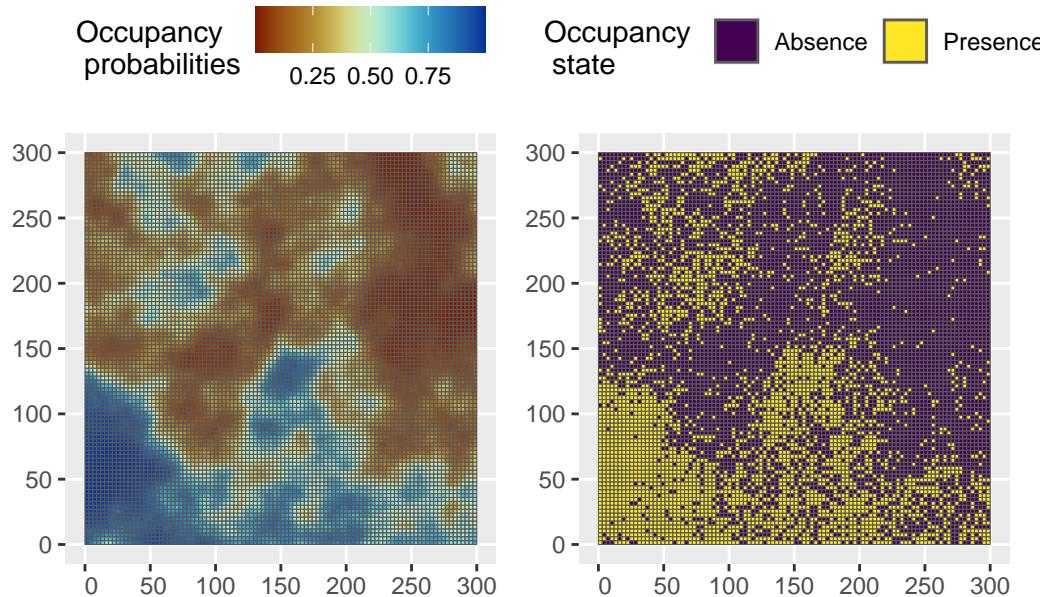


Figure 3: Simulated occupancy probabilities and true presence/absence state

Observational process model sub-component

Random sample of 20 % of the total cells and draw a random number of K visits per cell by setting a minimum of 1 and a maximum of 5 visits per site/cell.

```

# number of cells/sites in the sample
nsites = round(ncells*.20)
site_id = sample(1:ncells, size=nsites, replace=FALSE) # cell id
# add an indicator of whether a cell is in the sample or not
customGrid$sample <- ifelse(customGrid$cellid%in%site_id,1,0)

```

```

min_nvisits = 1 # minimum number of visits
max_nvisits = 5 # maximum number of visits
# Probabilities of drawing 1 thru 5 visits per site
probs = rep(1/length(min_nvisits:max_nvisits),length(min_nvisits:max_nvisits))
# Number of visits
nvisits = sample(min_nvisits:max_nvisits,nsites, prob = probs, replace = T)

```

Define model parameters α , detection probabilities p and observed number of occurrences per site y (Figure 4):

```

# Observational process model coefficients
alpha <- c(NA,NA)
alpha[1] <- qlogis(0.6) # Base line detection probability
alpha[2] <- 1 # detection covariate effect

# Detection probabilities
p <- inla.link.logit(alpha[1] + alpha[2]*g_s[site_id], inverse = T)
y <- rbinom(n = nsites,size = nvisits,prob = p*z[site_id] )

```

Create data set Table 1:

```

# centroid of the cell

Occ_data_1 <- customGrid |>
  st_centroid() |>
  filter(sample==1) |>
  dplyr::select(-c('sample'))

y_counts = data.frame(y = y , cellid = site_id, nvisits = nvisits)

Occ_data_1 <- left_join(Occ_data_1,y_counts,by = "cellid")

# append coordinates as columns

Occ_data_1[,c('x.loc','y.loc')] <- st_coordinates(Occ_data_1)
Occ_data_1 = st_drop_geometry(Occ_data_1)
# Save CSV file for analysis
write.csv(Occ_data_1,file='Occ_data_1.csv',row.names = F)

```

Table 1: First 6 entries of the occupancy data

cellid	y	nvisits	x.loc	y.loc
2	0	5	4.5	1.5
5	3	4	13.5	1.5
6	2	3	16.5	1.5
7	4	5	19.5	1.5
9	0	1	25.5	1.5
23	0	4	67.5	1.5

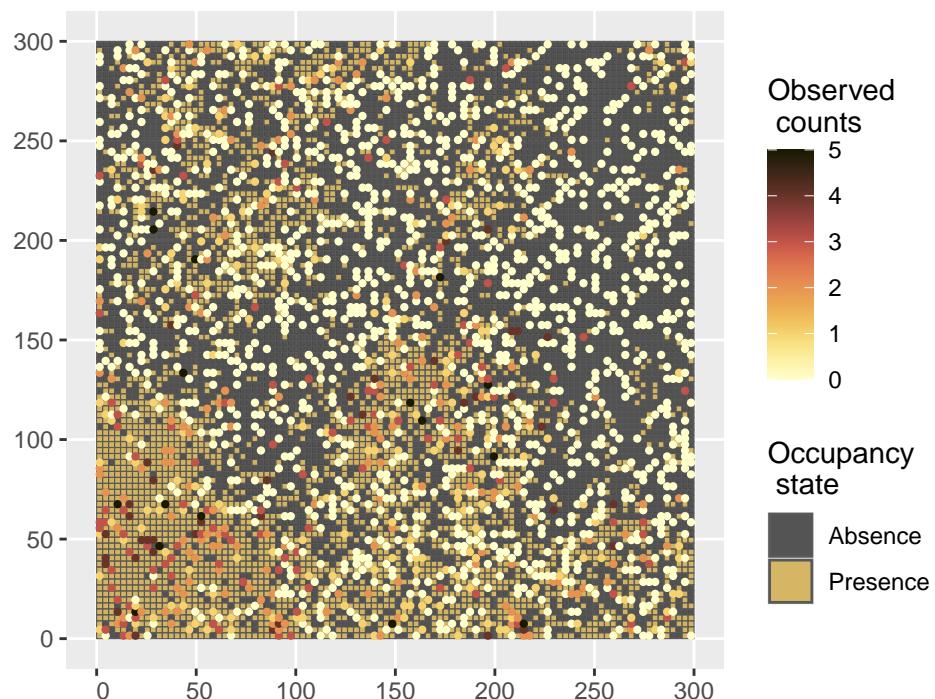


Figure 4: Number of times species was detected at sampled sites and true occupancy state.

Simulate space-time occupancy data

Here we simulate data for a space-time occupancy model by defining a SPDE for the spatial domain and an autoregressive model of order 1, i.e. AR(1), for the time component (this is separable space-time model where the spatio-temporal covariance is defined by the Kronecker product of the covariances of the spatial and temporal random effects, see (Cameletti et al. 2012) for more details).

We set a total of $nT = 5$ discrete time points where the occupancy state changes. We can use the `book.rspde()` function available in the `spde-book-functions.R` file (Kraainski et al. 2018) to simulate $t = 1, \dots, nT$ independent realizations of the random field¹. Then, temporal correlation is introduced:

$$\omega(s_i, t) = \rho \omega(s_i, t-1) + \epsilon(s_i, t),$$

where $\epsilon \sim N(0, \Sigma = \sigma_\epsilon^2 \tilde{\Sigma})$ are the spatially correlated random effects with Matérn correlation function $\tilde{\Sigma}$ and $\rho = 0.7$ is the autoregressive parameter ($\sqrt{1 - \rho^2}$ is included so $\omega(s_i, 1)$ comes from a $N(0, \Sigma/(1 - \rho^2))$ stationary distribution; see (Cameletti et al. 2012)).

```
# load helping functions

source('spde-book-functions.R')

# Time points
nT = 5
# parameters of the Matern

# Create a fine mesh
mesh_sim = fm_mesh_2d(loc.domain = st_coordinates(boundary_sf)[,1:2],
                      offset = c(-0.1, -.2),
                      max.edge = c(4, 50))
# Matern model
params <- c(sigma = sigma_spde, range = range_spde)

# generate samples from the random field

epsilon.t <- book.rspde(coord_grid, range = params[2], seed = seed,
                           sigma = params[1], n = nT, mesh = mesh_sim,
```

¹Note: If you are using INLA development version you might need modify the `book.rspde` function. Specifically, change the `inla.mesh.project` function to `fmesher::fm_evaluator` function to project the mesh into the domain coordinates.

```

    return.attributes = TRUE)

# temporal dependency
rho <- 0.65

omega_st <- epsilon.t

for (t in 2:nT){
  omega_st[, t] <- rho * omega_st[, t - 1] + sqrt(1 - rho^2) * epsilon.t[, t]
}

```

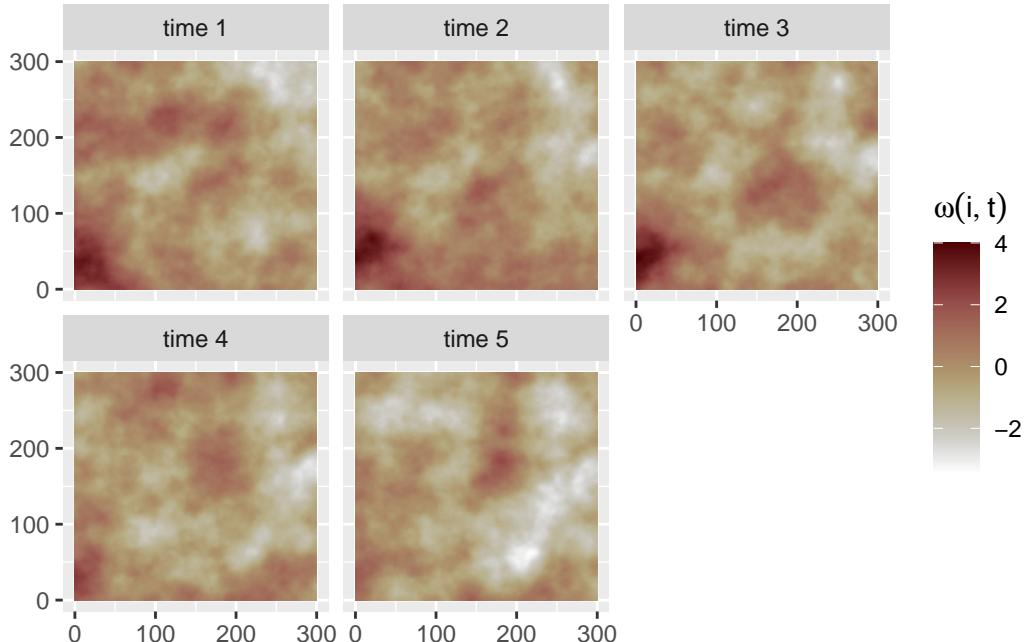


Figure 5: simulated spatio-temporal Gaussian field

Then we can simulate the occupancy state of cell i at time t (Figure 6) as follows:

$$\begin{aligned} z_{it} &\sim \text{Bernoulli}(\psi_{it}) \\ \text{logit}(\psi_{it}) &= \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \omega_{it}. \end{aligned} \tag{1}$$

```

# State process model coefficients
beta <- c(NA, NA, NA)
beta[1] <- qlogis(0.2) # Base line occupancy probability

```

```

beta[2] <- 0.75 # environmental covariate effect
beta[3] <- 1 # environmental covariate quadratic effect

z.mat = psi.mat = matrix(NA, ncol=nT, nrow=dim(coord_grid)[1])

for(t in 1:nT){
  # Occupancy probabilities
  psi.mat[,t] = inla.link.logit(beta[1] + beta[2]*x_s + beta[3]*x_s**2 + omega_st[,t], inv)
  # True occupancy state
  z.mat[,t] <- rbinom(ncells, size = 1, prob = psi.mat[,t])
}

```

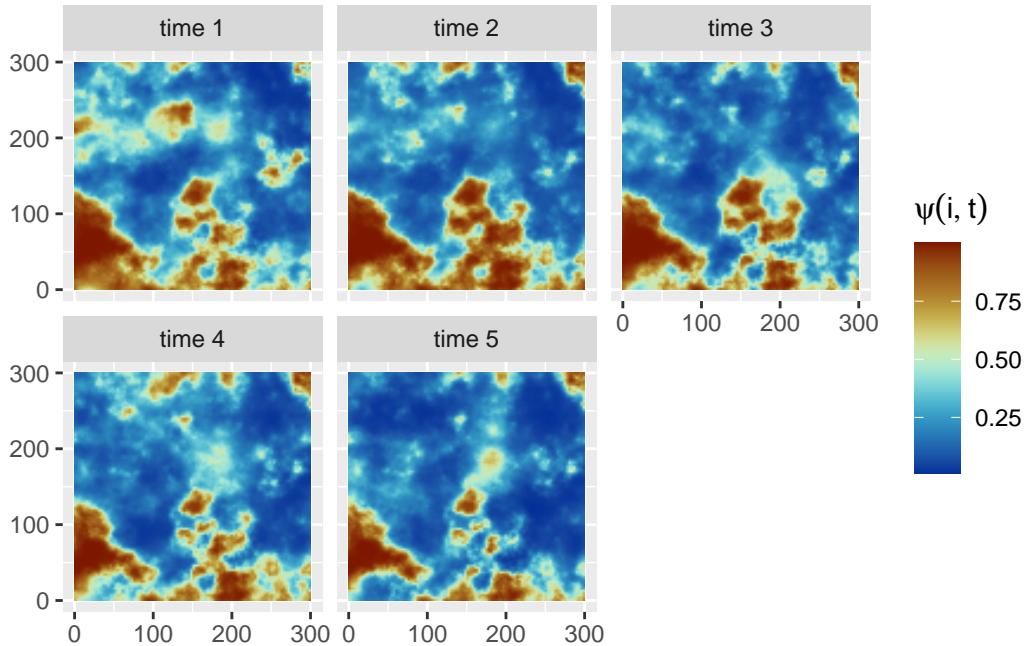


Figure 6: Simulated occupancy probabilities

Notice that we can use different locations at different times, e.g. when locations are not surveyed regularly. To simulate this we allow for some sites to be missing from the sample across years, by setting the minimum number of visits to zero . We also change the number of visits per year/site combination.

```

min_nvisits = 0 # minimum number of visits
max_nvisits = 5 # maximum number of visits
# Probabilities of drawing 1 thru 5 visits per site

```

```

probs = rep(1/length(min_nvisits:max_nvisits),length(min_nvisits:max_nvisits))
# Number of visits per site/year combination
nvisits.mat = matrix(NA,ncol=nT,nrow=nsites) # empty matrix to store the results

for(t in 1:nT){
  nvisits.mat[,t] = sample(min_nvisits:max_nvisits,nsites,
                           prob = probs, replace = T)
}

nvisits.mat[nvisits.mat==0]=NA # add NA for cells that were not visited

```

Now we compute the observed counts as before:

```

# Observational process model coefficients
alpha <- c(NA,NA)
alpha[1] <- qlogis(0.3) # Base line detection probability
alpha[2] <- -1.5 # detection covariate effect

y.mat = p.mat = matrix(NA,ncol=nT,nrow=nsites)

for(t in 1:nT){
  # Detection probabilities (constant through time)
  p.mat[,t] = inla.link.logit(alpha[1] + alpha[2]*g_s[site_id], inverse = T)
  # Observed occurrences
  y.mat[,t] <- suppressWarnings(rbinom(n = nsites, size = nvisits.mat[,t],
                                         prob = p.mat[,t]*z.mat[,t]))
}

```

Finally, create and save data set.

```

# centroid of the cell
Occ_data_2 <- suppressWarnings(customGrid |>
                                st_centroid() |>
                                filter(sample==1) |>
                                dplyr::select(-c('sample'))

# Add data
Occ_data_2[,paste('y',1:nT,sep='')] = y.mat # counts
Occ_data_2[,paste('nvisit',1:nT,sep='')] = nvisits.mat # visits per year

# append coordinates as columns
Occ_data_2[,c('x.loc','y.loc')] <- st_coordinates(Occ_data_2)

```

```

Occ_data_2 = st_drop_geometry(Occ_data_2)
# Save CSV file for analysis
write.csv(Occ_data_2,file='Occ_data_2.csv',row.names = F)

```

Spatially varying coefficients (SVC)

Here we simulate from a spatially varying coefficient model by adopting a space model with Matérn spatial covariance and a AR(1) time component. The same setting described for the space-time model will be used to drawn independent realization from the random field by using the `book.rMatern()` function. Then, temporal autocorrelation will be introduced to the dynamic regression coefficient β_t through the AR(1) structure described in the previous section (Note: The term $(1 - \rho^2)$ is added because of INLA internal AR(1) model parametrization; (Kraainski et al. 2018)).

```

# realization of the random field
set.seed(seed)
beta_t <- book.rMatern(nT, coord_grid, range = range_spde,
                       sigma = sigma_spde)

# introduce temporal correlation
beta_t[, 1] <- beta_t[, 1] / (1 - rho^2)

for (t in 2:nT) {
  beta_t[, t] <- beta_t[, t - 1] * rho + beta_t[, t] *
    (1 - rho^2)
}

```

Occupancy probabilities (Figure 7) are then defined on the logit scale as:

$$\text{logit}(\psi_{it}) = \beta_0 + \beta_1(i)t + \omega(i)$$

where $\omega(i)$ is the same field defined for the simple spatial occupancy model (Section). The detection probabilities and observed occurrences are simulated in the same way as before (see Section).

```

#|
set.seed(seed)

# intercept and mean of the effect
beta0 <- -1

```

```

z.mat = psi.mat = matrix(NA, ncol=nT, nrow=dim(coord_grid)[1])

for(t in 1:nT){
  # Occupancy probabilities
  psi.mat[,t] = inla.link.logit(beta0 + beta_t[,t] + omega_s, inverse = T)
  # True occupancy state
  z.mat[,t] <- rbinom(ncells, size = 1, prob = psi.mat[,t])
}

# simulate data

for(t in 1:nT){
  # Detection probabilities
  p.mat[,t] = inla.link.logit(alpha[1] + alpha[2]*g_s[site_id], inverse = T)
  # Observed occurrences
  y.mat[,t] <- rbinom(n = nsites,
                      size = nvisits.mat[,t],
                      prob = p.mat[,t]*z.mat)
}

# centroid of the cell
Occ_data_3 <- customGrid |>
  st_centroid() |>
  filter(sample==1) |>
  dplyr::select(-c('sample'))

# Add data
Occ_data_3[,paste('y',1:nT,sep='')] = y.mat # counts
Occ_data_3[,paste('nvisit',1:nT,sep='')] = nvisits.mat # visits per year

# append coordinates as columns
Occ_data_3[,c('x.loc','y.loc')] <- st_coordinates(Occ_data_3)
Occ_data_3 = st_drop_geometry(Occ_data_3)
# Save CSV file for analysis
write.csv(Occ_data_3,file='Occ_data_3.csv',row.names = F)

```

Cameletti, Michela, Finn Lindgren, Daniel Simpson, and Håvard Rue. 2012. “Spatio-Temporal Modeling of Particulate Matter Concentration Through the SPDE Approach.” *AStA Advances in Statistical Analysis* 97 (2): 109–31. <https://doi.org/10.1007/s10182-012-0196-3>.

Krainski, Elias, Virgilio Gómez-Rubio, Haakon Bakka, Amanda Lenzi, Daniela Castro-Camilo,

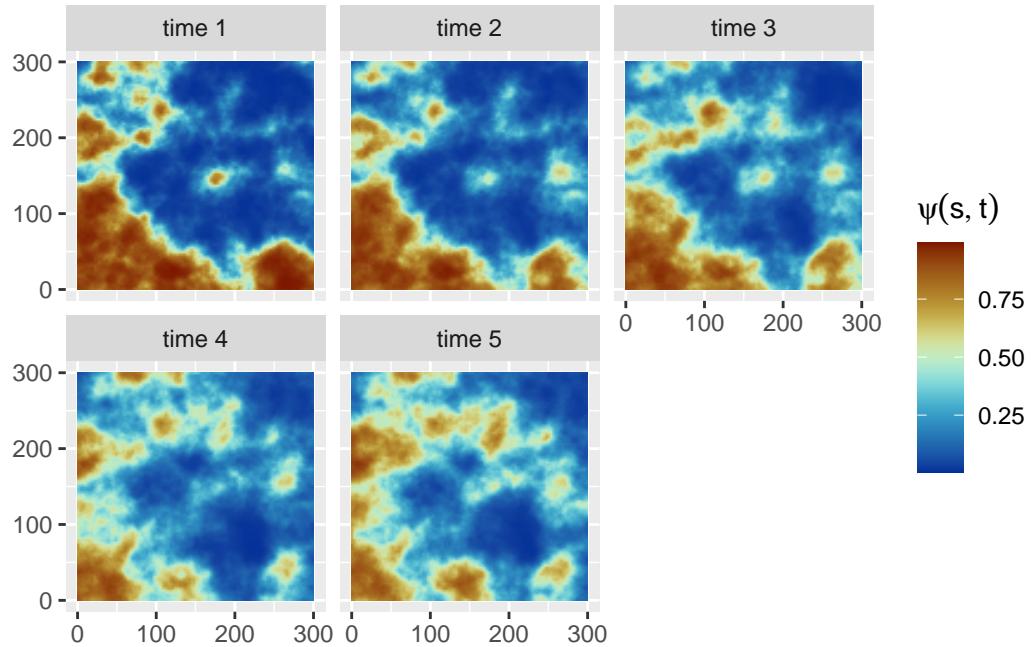


Figure 7: Simulated occupancy probabilities from a SVC model

Daniel Simpson, Finn Lindgren, and Håvard Rue. 2018. *Advanced Spatial Modeling with Stochastic Partial Differential Equations Using r and INLA*. Chapman; Hall/CRC. <https://doi.org/10.1201/9780429031892>.